The Bayes factor surface for searches for new physics

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Context



- I am a particle physicist phenomenologist
- I began my Ph.D. around start of Large Hadron Collider (LHC) in 2009
- Focused on statistical analyses of supersymmetric models in light of first LHC data and direct searches for dark matter (Fowlie, 2013)
- Early in Ph.D., studied statistical methods in physics from these two books

Searches for new physics



- Want to search for a signal on top of a noisy background
- Signal model usually parameterised by an effect size, e.g., a cross section for the production of a new particle
- Background model often equivalent to effect size = 0
- Could be nuisance parameters describing systematic uncertainties
- Signal model could have other unknown parameters, e.g. the unknown mass of a new particle

Statistical practices in searches for new physics

In particle physics, experimental results of searches for new particles are shown by

- Confidence intervals for effect size (e.g. cross section) and other parameters of interest
- P-values for discovery of new particles

This is done through

- Statistical recipes using Wilks' theorem; see Cowan et al., 2011. These recipes are popular — about 500 cites/year
- Exact prescriptions and conventions still debated see PHYSTAT-DM 2019, about 50 participant workshop for conventions for dark matter searches
- Led to recommendations paper on confidence intervals (Baxter et al., 2021)

Definition

An interval found from a procedure that, under repeated sampling, would include the true value of the unknown parameter at a guaranteed rate (Neyman, 1937).

- The desired rate is known as the confidence level, and 90% and 95% are common choices
- Procedures that guarantee that the rate is exactly the confidence level are known as exact
- Those that guarantee that the rate at least as great as the confidence level are known as valid

Search for dark matter

Result from LZ shown as a one-sided confidence interval (upper limit) on cross section (an effect size) as function of mass (Aalbers et al., 2023)



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Properties of confidence intervals are not always satisfactory, even to adherents:

- Flip-flopping coverage spoilt by choosing between one- or two-tailed limits after seeing data
- False exclusion confidence intervals exclude effect sizes at rate of e.g., 5%. Including arbitrarily tiny effect sizes to which the experiment had no power
- Systematics hard to handle nuisance parameters describing systematic uncertainties



Can of worms



On more general and philosophical grounds, in my opinion,

- Whole frequentist edifice is full of thinking traps
- Prone to misinterpretation hard to interpret or communicate a confidence interval (Morey et al., 2016)
- Informal interpretation that effect sizes outside CI are ruled out or implausible — hard to justify

Easy to criticise confidence intervals. Can we do better?

- Obviously, I wanted to be Bayesian
- The Bayesian analogue of the confidence interval the credible region (Jaynes, 1989a)!

Definition

A credible region, \mathcal{R} , contains a specified percentile of posterior probability, e.g., 95%,

$$\int_{\mathcal{R}} p(\theta \,|\, x, M) \,\mathrm{d}\theta = 0.95$$

for parameter θ , data x and model M.



In this context, credible regions are not much better

- **Depend on ordering rule** which region \mathcal{R} ?
- This induces a dependence on parametrization
- Sensitive to arbitrary aspects of the prior
- Cannot tell us whether a model predicting particular mass and cross section any better than background-only model
- This is connected to fact that there is no duality between testing and measurement



For a while I was stumped.

- If you don't like the answer, perhaps you asked the wrong question (Jaynes, 1989b)
- What question do we want to ask?

We don't like the credible region, because it answers the wrong question. We don't want to know the plausible parameters in a dummy model of (mass, cross section).

The question is: how do choices of (mass, cross section) compare to the background only model?



Bayes factor surface

Definition

For parameters θ and data x, compute the Bayes factor

$$B_{10}(\theta) \equiv \frac{p(x \mid \theta, H_1)}{p(x \mid H_0)},$$

Show results of search by contours of $B_{10}(\theta)$. E.g., the contour of θ for which $B_{10}(\theta) = 1/10$.

- Does not depend a choice of prior, parametrization or ordering rule
- Directly tells us change in plausibility of model predicting particular parameters θ relative to background only model

Back to direct detection of dark matter

We compute the Bayes factor surface, as well as confidence limits



We can tell by eye change in plausibility of models making particular predictions

Searches for supersymmetry

Because the idea is simple and general, it works in many other cases. E.g., an LHC search for supersymmetric particles



Do any fundamental theories make predictions in the purple region?

Cosmological inflation

Here is another example: models of inflation in light of Planck measurements of the CMB



Models inside the 95% CR are have BF of about 1

There are often nuisance parameters, such that we cannot just directly compute the Bayes factor surface; we need to marginalise

In searches for new physics, models are often nested.

- This means that we can use a Savage-Dickey ratio (Dickey, 1971) to compute the Bayes factor surface
- Compute posterior usually conventional methods, e.g., Markov Chain Monte Carlo
- Use e.g., kernel density representation of posterior and identity

$$B_{10}(\theta) = \frac{p(x \mid \theta)}{p(x \mid \theta_0)} = \frac{p(\theta \mid x)}{p(\theta_0 \mid x)} \frac{\pi(\theta_0)}{\pi(\theta)}$$

where θ_0 correspond to background-only model

Bayesian computation can be challenging. There is no reason that machinery developed to compute posterior (e.g., MCMC) should be appropriate for Bayes factor surface

 What if, for illustration, we want to compute contours at e.g., B = 1/1000? Far into the tails of the posterior. We would require an enormous effective sample size

I have a hunch that nested sampling (Ashton et al., 2022) may be valuable here because it produces weighted samples from tails.

Bayesian computation can be challenging. There is no reason that machinery developed to compute posterior (e.g., MCMC) should be appropriate for Bayes factor surface

What if our models are not nested?

Computing a Bayes factor (e.g., by nested sampling) at each node on a grid doesn't sound great; can we do better?

Bayesian computation can be challenging. There is no reason that machinery developed to compute posterior (e.g., MCMC) should be appropriate for Bayes factor surface

• What if, pre-data, we want to know median expected Bayes factor surface assuming no new physics?

Can we use the Asimov trick and compute Bayes factor surface with data = median from background only model?

When I wrote the paper, I knew that

- Bayes factor surface had been proposed as a tool to study prior sensitivity — show the change in Bayes factor when changing e.g., width of prior
- Bayes factor function had been proposed (Johnson, Pramanik, and Shudde, 2023) — one-dimensional and motivations somewhat unclear to me

Since writing the paper,

- I found the NANOGrav paper that uses a similar construction
- Samuel contacted me to bring to my attention relevant works from the recent statistics literature

A rose by any other name

- Bayes factor surface
- Bayes factor function
- Support interval
- K-ratio

Name will settle as idea matures



- Bayes factor surface simple and intuitive way to summarise searches for new physics
- Shows change in plausibility of choices of model parameters relative to background only model
- Wide-ranging applications across physics and beyond
- Idea popping up independently in various contexts
- Computational methods and some properties (e.g., frequentist properties) in their infancy

A new tool to present results of searches for new physics!

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